

# Chapter 3



Dynamic Programming

&

Catalan Numbers

برنامه‌نویسی پویا و اعداد کاتالان

## چه زمانی روش تقسیم و حل ناکارآمد است؟

### □ پس از تقسیم ...

■ مسایل کوچکتر باهم ارتباط ندارند؛ مانند جستجوی ادغامی  
□ در این حالت تقسیم و حل مناسب است.

■ مسایل کوچکتر باهم ارتباط دارند؛ مانند رشته فیبوناچی  
□ در این حالت تقسیم و حل مناسب نیست. زیرا یک مساله به صورت تکراری حل می‌شود.

### □ برنامه نویسی پویا

■ روشی پایین به بالا

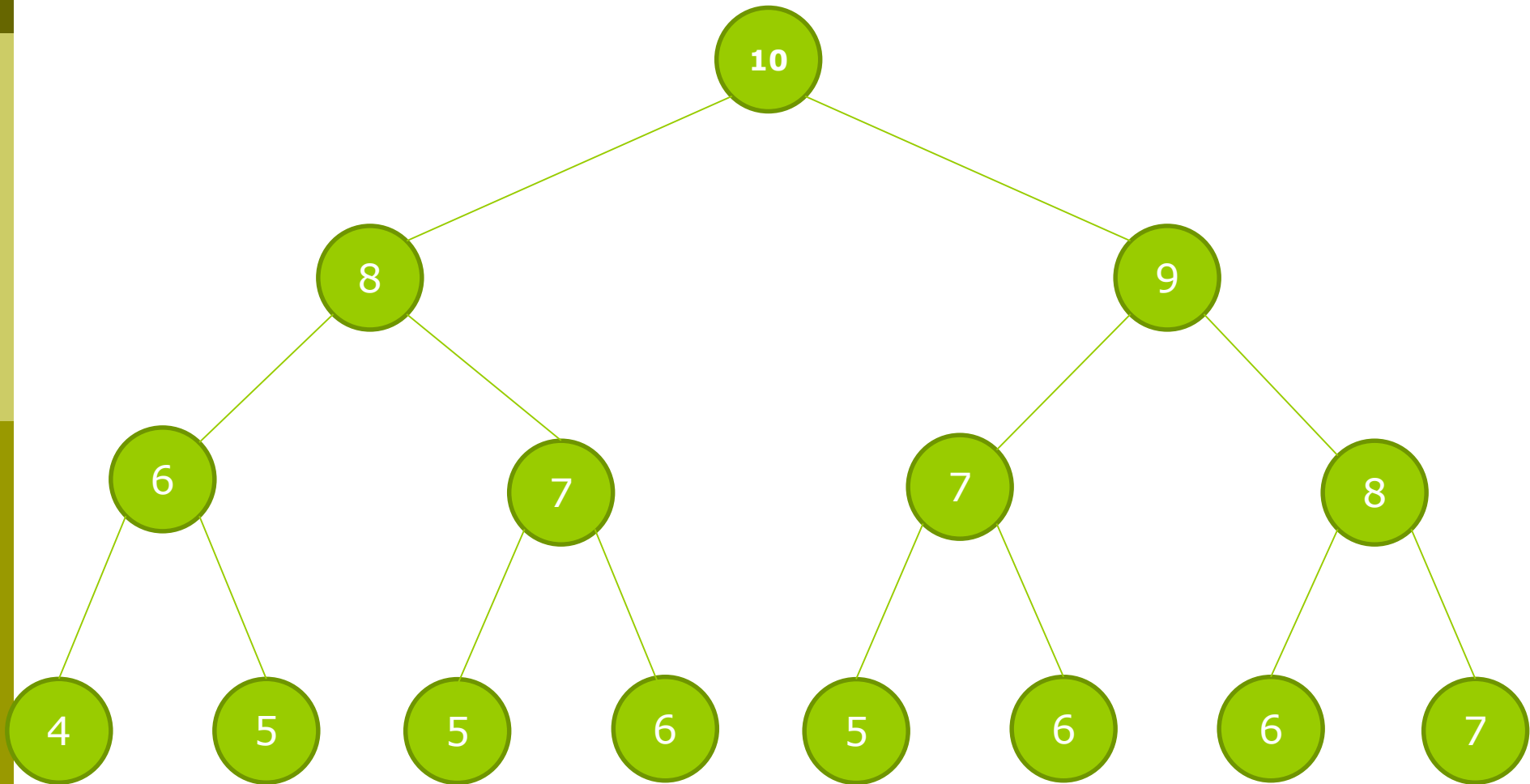
■ bottom-up approach

■ نیاز به ساختمان داده مناسب برای ذخیره سازی راه‌حل‌های میانی

# فیبوناچی

چندین حل تکراری برای محاسبه یک مقدار

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# الگوریتم فیبوناچی - یادآوری

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- Algorithm 1.7: *n*th Fibonacci Term (Iterative)

```
int fib2 (int n) {  
    index i;  
    int f[0 .. n];  
    f[ 0 ] = 0;  
    if (n > 0){  
        f[ 1 ] = 1;  
        for (i = 2; i <= n; i++)  
            f[ i ] = f[i - 1] + f [i -2 ]; }  
    return f[ n ];  
}
```

## گام‌های حل مساله

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- ایجاد یک رابطه بازگشتی برای حل مساله
- حل این رابطه بازگشتی به صورت پایین به بالا

# The binomial coefficient

## ضرایب دو جمله‌ای

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### □ Definition

$$\binom{n}{k} = \frac{n!}{k!(n-k)!} \quad \text{for } 0 \leq k \leq n$$

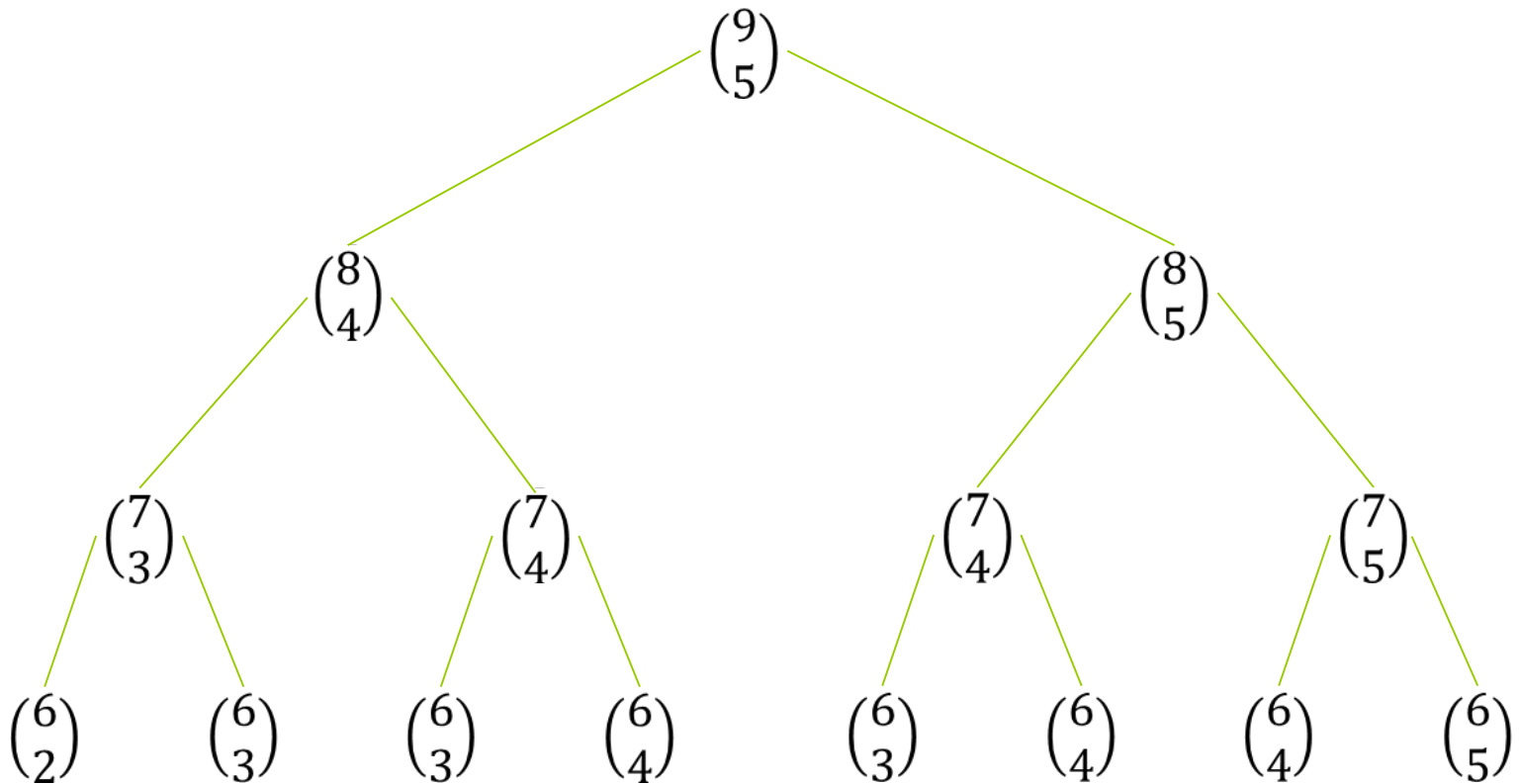
### □ Recursive definition

$$\binom{n}{k} = \begin{cases} \binom{n-1}{k-1} + \binom{n-1}{k} & 0 < k < n \\ 1 & k = 0 \text{ or } k = n \end{cases}$$

# The binomial coefficient

$$\binom{n}{k} = \begin{cases} \binom{n-1}{k-1} + \binom{n-1}{k} & 0 < k < n \\ 1 & k = 0 \text{ or } k = n \end{cases}$$

---



# Binomial Coefficient

## Using Divide-and-Conquer

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```
int bin (int n, int k) {  
    if ( k == 0 || n == k)  
        return 1;  
    else  
        return bin (n-1, k - 1)+bin (n - 1, k);  
}
```



# Using dynamic programming

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- استفاده از آرایه **B** برای ذخیره سازی ضرایب
- گام‌ها

■ ایجاد رابطه بازگشتی

$$B[i][j] = \begin{cases} B[i-1][j-1] + B[i-1][j] & 0 < j < i \\ 1 & j = 0 \text{ or } j = i \end{cases}$$

■ حل به صورت پایین به بالا

	0	1	2	3	4	$j$	$k$
0	1						
1	1	1					
2	1	2	1				
3	1	3	3	1			
4	1	4	6	4	1		
$i$							
$n$							

$$\begin{array}{ccc}
 B[i-1][j-1] & B[i-1][j] & \\
 \downarrow & \downarrow & \\
 \rightarrow & B[i][j] & 
 \end{array}$$

# Binomial Coefficient Using Dynamic Programming

---

```
int bin2 (int n, int k) {  
    index i, j;  
    int B[0..n] [0..k];  
    for (i = 0; i <= n; i++)  
        for (j = 0; j <= minimum (i, k); j++)  
            if (j == 0 || j == i)  
                B[i][j] = 1;  
            else  
                B[i][j] = B[i - 1][j - 1] + B[i - 1][j];  
    return B[n][k];  
}
```

# Time complexity

---

- The number of passes through the for- $j$  loop for each value of  $i$

$i$	0	1	2	3	...	$k$	$k+1$	...	$n$
Number of passes	1	2	3	4	...	$k+1$	$k+1$	...	$k+1$

$$1 + 2 + 3 + 4 + \dots + k + \underbrace{(k+1) + (k+1) + \dots + (k+1)}_{n-k+1 \text{ times}} =$$

$$\frac{k(k+1)}{2} + (n-k+1)(k+1) = \frac{(2n-k+2)(k+1)}{2} \in \Theta(nk)$$

# Floyd's algorithm for shortest paths

کوتاهترین راه از هر شهر به شهر دیگر

مساله‌ای که مسافران هوایی با آن مواجه هستند، تعیین کوتاه‌ترین راه برای پرواز از شهری به شهر دیگر است.

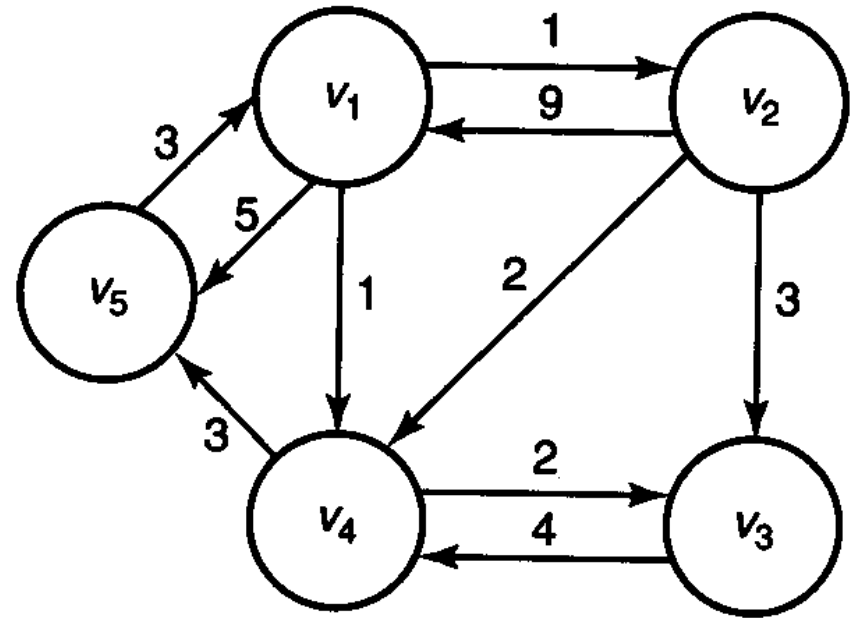


Figure 3.2 • A weighted, directed graph.

# مساله بهينه سازي

## Optimization Problem

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### □ تعريف:

- بيش از يك راه حل وجود داشته باشد.
- هر راه حل هزينه‌اي دارد.
- هدف، يافتن راه حل با كمترين هزينه است.
- مساله فلويد يك مساله بهينه‌سازي است.

# نمایش گراف با استفاده از یک ماتریس مجاورت (Adjacency matrix)

$$W[i][j] = \begin{cases} \text{weight on edge if there is an edge from } v_i \text{ to } v_j \\ \infty \text{ if there is no edge from } v_i \text{ to } v_j \\ 0 \text{ if } i = j \end{cases}$$

	1	2	3	4	5
1	0	1	$\infty$	1	5
2	9	0	3	2	$\infty$
3	$\infty$	$\infty$	0	4	$\infty$
4	$\infty$	$\infty$	2	0	3
5	3	$\infty$	$\infty$	$\infty$	0

*W*

	1	2	3	4	5
1	0	1	3	1	4
2	8	0	3	2	5
3	10	11	0	4	7
4	6	7	2	0	3
5	3	4	6	4	0

*D*

Figure 3.3 • *W* represents the graph in Figure 3.2 and *D* contains the lengths of the shortest paths. Our algorithm for the Shortest Paths problem computes the values in *D* from those in *W*.

## الگوریتم فلویڈ

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- Create a sequence of  $n+1$  arrays  $D^{(k)}$ , where  $0 \leq k \leq n$  and where
$$D^{(k)}[i][j] = \text{length of a shortest path from } v_i \text{ to } v_j \text{ using only vertices in the set } \{v_1, v_2, \dots, v_k\} \text{ as intermediate vertices}$$
$$D^{(0)} = W \text{ and } D^{(n)} = D$$
- Try to determine  $D[2][5]$



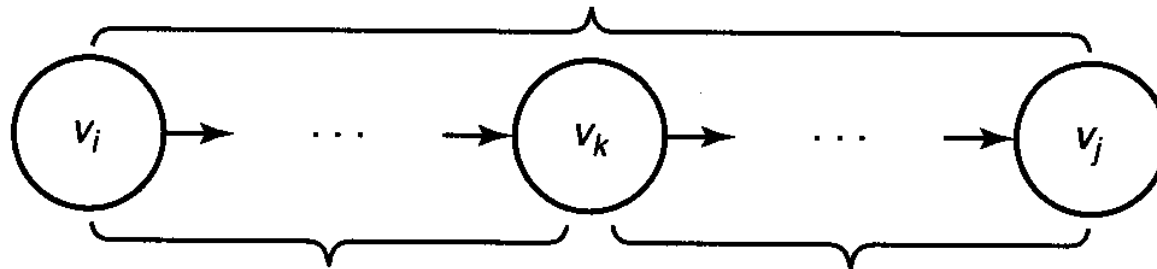
# To compute $D^{(k)}$ from $D^{(k-1)}$

---

- Case 1. At least one shortest path from  $v_i$  to  $v_j$ , using only vertices in  $\{v_1, v_2, \dots, v_k\}$  as intermediate vertices, does not use  $v_k$ . Then  $D^{(k)}[i][j] = D^{(k-1)}[i][j]$
- Case 2. All shortest paths from  $v_i$  to  $v_j$ , using only vertices in  $\{v_1, v_2, \dots, v_k\}$  as intermediate vertices, do use  $v_k$ . Then  $D^{(k)}[i][j] = D^{(k-1)}[i][k] + D^{(k-1)}[k][j]$

# Put together

A shortest path from  $v_i$  to  $v_j$  using only vertices in  $\{v_1, v_2, \dots, v_k\}$



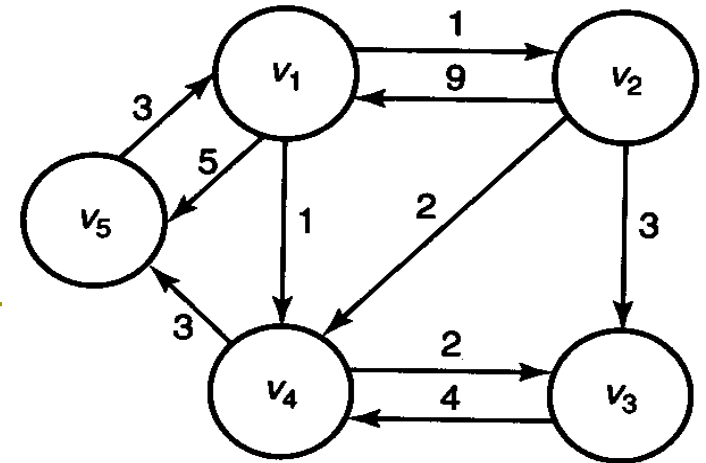
A shortest path from  $v_i$  to  $v_k$  using only vertices in  $\{v_1, v_2, \dots, v_k\}$

A shortest path from  $v_k$  to  $v_j$  using only vertices in  $\{v_1, v_2, \dots, v_k\}$

Figure 3.4 • The shortest path uses  $v_k$ .

- $D^{(k)}[i][j] = \text{minimum}(D^{(k-1)}[i][j], D^{(k-1)}[i][k] + D^{(k-1)}[k][j])$
- Try to compute  $D^{(2)}[5][4]$

$$D^0 = \begin{bmatrix} 0 & 1 & \infty & 1 & 5 \\ 9 & 0 & 3 & 2 & \infty \\ \infty & \infty & 0 & 4 & \infty \\ \hline \infty & \infty & 2 & 0 & 3 \\ 3 & \infty & \infty & \infty & 0 \end{bmatrix}$$



$$D^1[1][2] = \text{Min}\{D^0[1][2], D^0[1][1] + D^0[1][2]\} = 1$$

$$D^1[1][3] = \text{Min}\{D^0[1][3], D^0[1][1] + D^0[1][3]\} = \infty$$

$$D^1[1][4] = \text{Min}\{D^0[1][4], D^0[1][1] + D^0[1][4]\} = 1$$

$$D^1[1][5] = \text{Min}\{D^0[1][5], D^0[1][1] + D^0[1][5]\} = 5$$

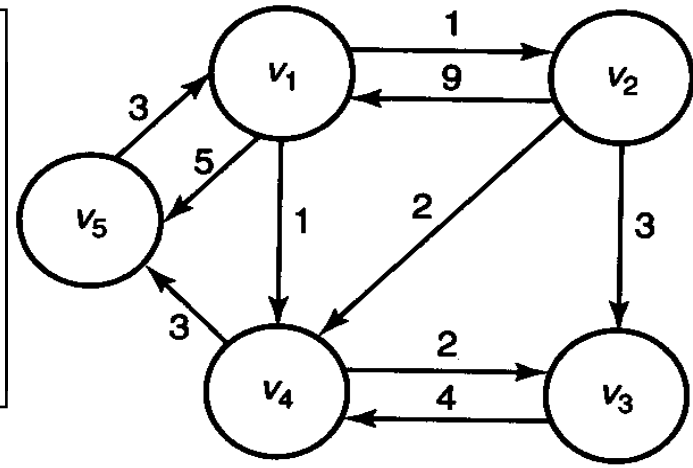
$$D^1[2][1] = \text{Min}\{D^0[2][1], D^0[2][1] + D^0[1][1]\} = \text{Min}\{9, 9 + 0\} = 9$$

$$D^1[2][3] = \text{Min}\{D^0[2][3], D^0[2][1] + D^0[1][3]\} = \text{Min}\{3, 9 + \infty\} = 3$$

$$D^1[2][4] = \text{Min}\{D^0[2][4], D^0[2][1] + D^0[1][4]\} = \text{Min}\{2, 9 + 1\} = 2$$

$$D^1[2][5] = \text{Min}\{D^0[2][5], D^0[2][1] + D^0[1][5]\} = \text{Min}\{\infty, 9 + 5\} = 14$$

$$D^0 = \begin{bmatrix} 0 & 1 & \infty & 1 & 5 \\ 9 & 0 & 3 & 2 & \infty \\ \infty & \infty & 0 & 4 & \infty \\ \infty & \infty & 2 & 0 & 3 \\ 3 & \infty & \infty & \infty & 0 \end{bmatrix} \quad D^1 = \begin{bmatrix} 0 & 1 & \infty & 1 & 5 \\ 9 & 0 & 3 & 2 & \underline{14} \\ \infty & \infty & 0 & 4 & \infty \\ \infty & \infty & 2 & 0 & 3 \\ 3 & \underline{4} & \infty & \underline{4} & 0 \end{bmatrix}$$



$$D^2 = \begin{bmatrix} 0 & 1 & \underline{4} & 1 & 5 \\ 9 & 0 & 3 & 2 & 14 \\ \infty & \infty & 0 & 4 & \infty \\ \infty & \infty & 2 & 0 & 3 \\ 3 & 4 & \underline{7} & 4 & 0 \end{bmatrix} \quad D^3 = \begin{bmatrix} 0 & 1 & 4 & 1 & 5 \\ 9 & 0 & 3 & 2 & 14 \\ \infty & \infty & 0 & 4 & \infty \\ \infty & \infty & 2 & 0 & 3 \\ 3 & 4 & 7 & 4 & 0 \end{bmatrix}$$

$$D^4 = \begin{bmatrix} 0 & 1 & 3 & 1 & \underline{4} \\ 9 & 0 & 3 & 2 & \underline{5} \\ \infty & \infty & 0 & 4 & \underline{7} \\ \infty & \infty & 2 & 0 & 3 \\ 3 & 4 & \underline{6} & 4 & 0 \end{bmatrix} \quad D^5 = \begin{bmatrix} 0 & 1 & 3 & 1 & 4 \\ \underline{8} & 0 & 3 & 2 & 5 \\ \underline{10} & \underline{11} & 0 & 4 & 7 \\ \underline{6} & \underline{7} & 2 & 0 & 3 \\ 3 & 4 & 6 & 4 & 0 \end{bmatrix}$$

# The algorithm

---

```
void floyd (int n, const number W[],[], number D[],[])  
{  
  index i, j, k;  
  D = W;  
  for (k = 1; k <= n; k++)  
    for (i = 1; i <= n; i++)  
      for (j = 1; j <= n; j++)  
        D[i][j] = minimum(D[i][j], D[i][k] + D[k][j]);  
}
```

# Every-case time complexity

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- Basic operation: The instruction (if) in the for- $j$  loop
- Input size:  $n$ , the number of vertices in the graph
- Time complexity:  
$$T(n) = n \times n \times n = n^3 \in \Theta(n^3)$$

# Floyd's algorithm for shortest paths

---

```
void floyd2 (int n, const number W[][i], number D[][i],
             index P[][i])
{
    index, i, j, k;
    for(i = 1; i <= n; i++)
        for (j = 1; j <= n; j++)
            P[i][j] = 0;

    D = W
    for (k = 1; k <= n; k++)
        for(i = 1; i <= n; i++)
            for(j = 1; j <= n; j++)
                if (D[i][k] + D[k][j] < D[i][j]) {
                    P[i][j] = k;
                    D[i][j] = D[i][k] + D[k][j]; }
}
```

# Sample output

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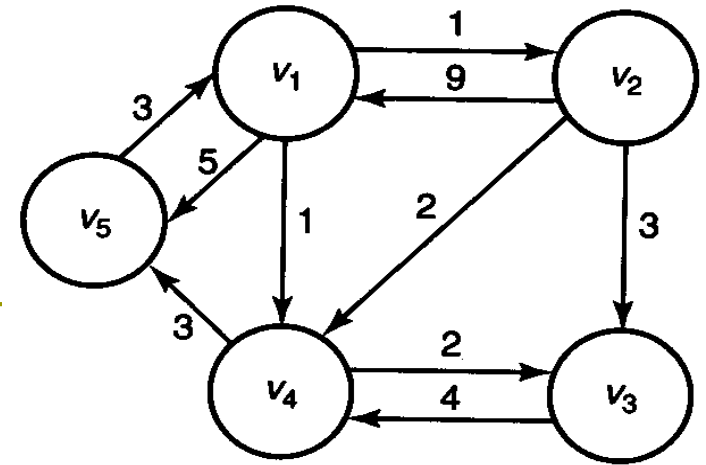
□ ماتریس  $P$  برای یافتن مسیر بهینه

	1	2	3	4	5
1	0	0	4	0	4
2	5	0	0	0	4
3	5	5	0	0	4
4	5	5	0	0	0
5	0	1	4	1	0

Figure 3.5 • The array  $P$  produced when Algorithm 3.4 is applied to the graph in Figure 3.2.



## نمایش کوتاهترین مسیر

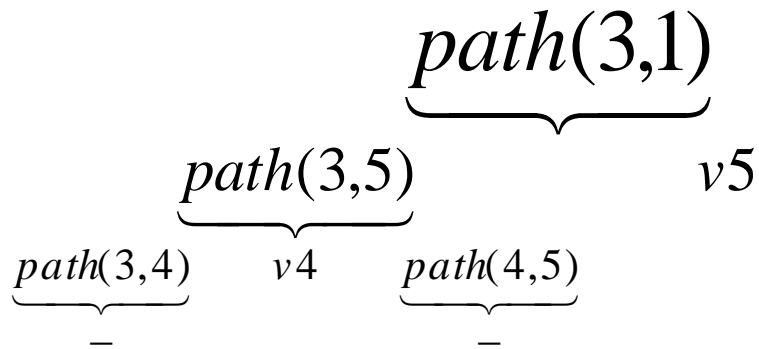
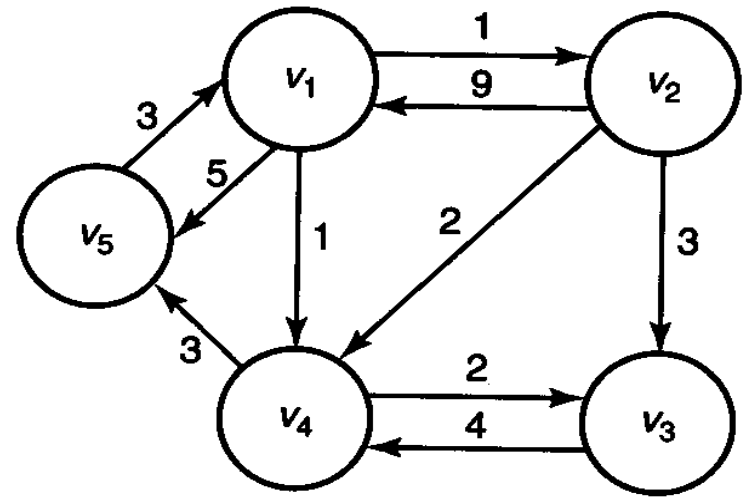


```
void path (index q, r)
{
    if (P[ q ] [ r ] != 0){
        path (q, P[q] [r]);
        cout << "v" << P[ q ] [ r ];
        path (P[ q ] [ r ], r);
    }
}
```

Try to determine path(5,3)

```
void path (index q, r)
```

```
{
  if (P[q][r] != 0)
  {
    path (q, P[q][r]);
    cout << "v" << P[q][r];
    path (P[q][r], r);
  }
}
```



$path(5,1)$

	1	2	3	4	5
1	0	0	4	0	4
2	5	0	0	0	4
3	5	5	0	0	4
4	5	5	0	0	0
5	0	1	4	1	0

# Dynamic programming and optimization problems

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## □ گام‌ها برای حل یک مساله به روش پویا

■ یافتن یک رابطه بازگشتی که راه حل بهینه را به دست دهد.

■ محاسبه هزینه راه حل بهینه به روش پایین به بالا

■ یافتن راه حل بهینه (مسیر بهینه) به روش پایین به بالا

# Principle of optimality

اصل بهینگی – (اختیاری)

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The optimal solution to the instance  
contains optimal solutions to all  
subinstances

# Principle of optimality (Example)

---

if  $v_k$  is a vertex on an optimal path from  $v_i$  to  $v_j$ , then the subpaths from  $v_i$  to  $v_k$  and from  $v_k$  to  $v_j$  must also be optimal.

# Principle of optimality

---

It is necessary to show that the principle applies before using dynamic programming to obtain the solution

# Longest simple paths problem

- The longest path from  $v_1$  to  $v_4$  is  $[v_1, v_3, v_2, v_4]$ . However, the subpath  $[v_1, v_3]$  is not optimal

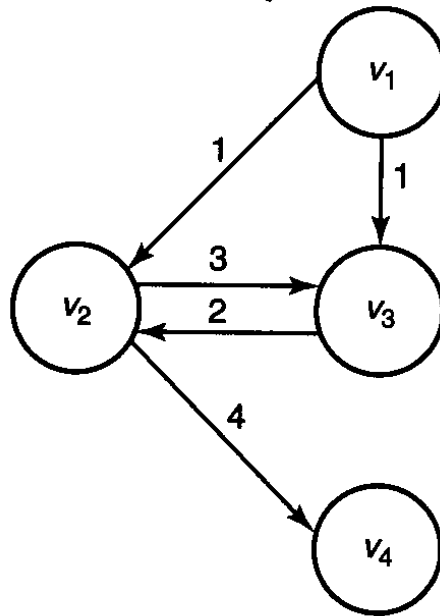


Figure 3.6 • A weighted, directed graph with a cycle.

# ضرب زنجیره‌ای ماتریس‌ها

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- To multiply an  $i \times j$  matrix times a  $j \times k$  matrix, the number of elementary multiplications is:  $i \times j \times k$  (why?)
- ترتیب‌های (اولویت‌بندی‌های) مختلفی برای ضرب چند ماتریس درهم وجود دارد که در نتیجه تعداد ضرب لازم متفاوت خواهد بود.



# Example

---

$A \times B \times C \times D$   
 $20 \times 2 \quad 2 \times 30 \quad 30 \times 12 \quad 12 \times 8$

$A(B(CD)) \Rightarrow$  The number of multiplications = 3680

$A((BC)D)$  1232

$(AB)(CD)$  8880

$(A(BC))D$  3120

$((AB)C)D$  10320

# Using dynamic programming

---

## □ Some properties

- the number of columns in  $A_{k-1}$  equals the number of rows in  $A_k$
- We can let  $d_0$  be the number of rows in  $A_1$  and  $d_k$  be the number of columns in  $A_k$  for  $1 \leq k \leq n$ , the dimension of  $A_k$  is  $d_{k-1} \times d_k$

# Introducing a sequence of arrays

- $M[i][j]$  = minimum number of multiplications needed to multiply  $A_i$  through  $A_j$ , if  $i < j$ .
- $M[i][i] = 0$
- Example

$$\begin{array}{cccccc} A_1 & \times & A_2 & \times & A_3 & \times & A_4 & \times & A_5 & \times & A_6 \\ 5 \times 2 & & 2 \times 3 & & 3 \times 4 & & 4 \times 6 & & 6 \times 7 & & 7 \times 8 \\ d_0 & d_1 & d_1 & d_2 & d_2 & d_3 & d_3 & d_4 & d_4 & d_5 & d_5 & d_6 \end{array}$$

What is  $M[4][6]$ ?

# To multiply 6 matrices

---

## □ Possible factorizations

- $A_1 ( A_2 A_3 A_4 A_5 A_6 )$
- $( A_1 A_2 ) ( A_3 A_4 A_5 A_6 )$
- $( A_1 A_2 A_3 ) ( A_4 A_5 A_6 )$
- $( A_1 A_2 A_3 A_4 ) ( A_5 A_6 )$
- $( A_1 A_2 A_3 A_4 A_5 ) A_6$

ضرب آخر

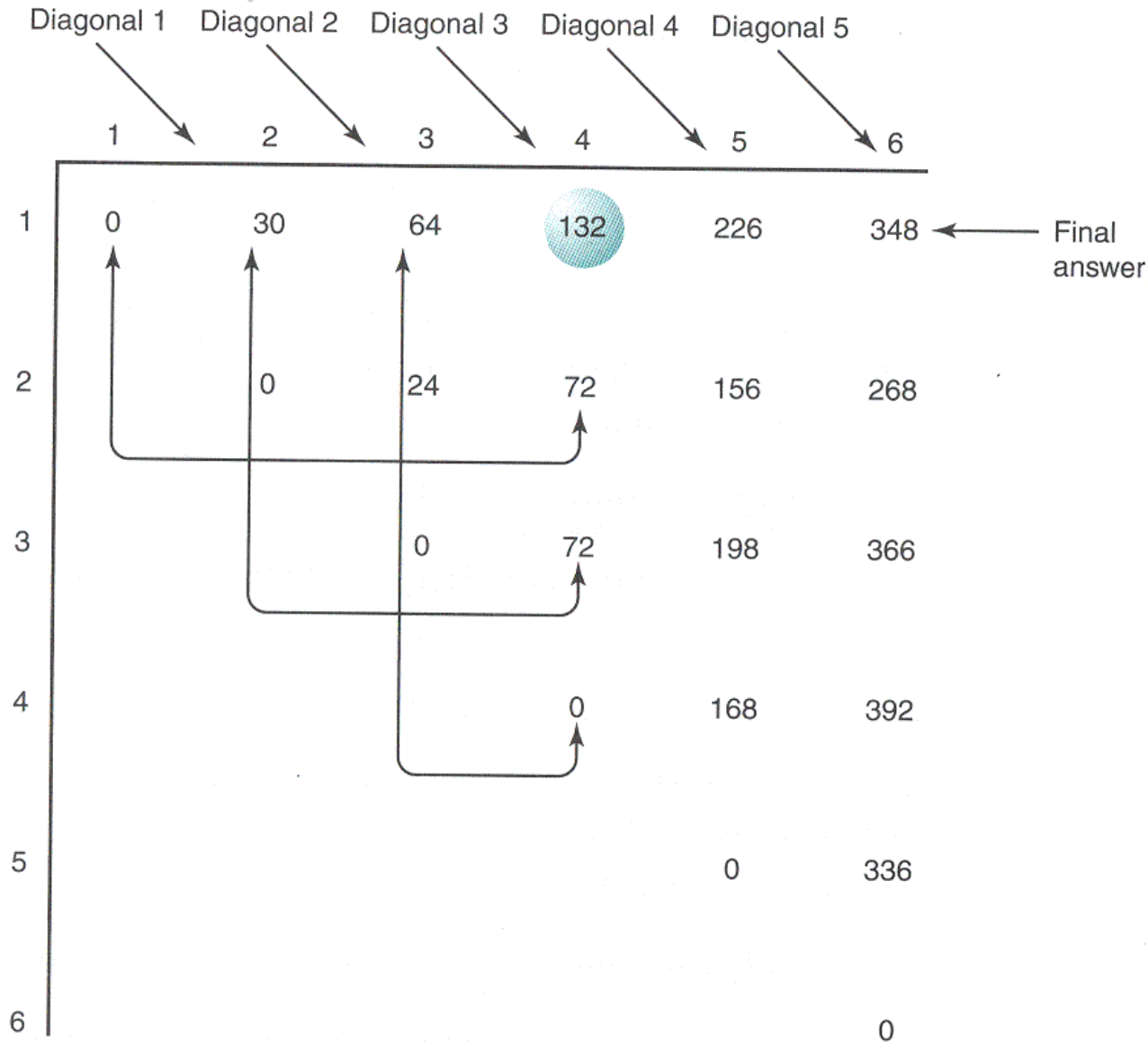
## □ The number of multiplications for the $k$ th factorization:

$$M[1][k] + M[k+1][6] + d_0 d_k d_6$$

## □ Therefore (Recursive Equation)

$$M[1][6] = \min_{1 \leq k \leq 5} (M[1][k] + M[k+1][6] + d_0 d_k d_6)$$

$$\left\{ \begin{aligned} M[i][j] &= \min_{i \leq k \leq j-1} (M[i][k] + M[k+1][j] + d_{i-1}d_kd_j), \quad \text{if } i < j \\ M[i][i] &= 0 \end{aligned} \right.$$



# Example

---

$$M[1][3] = \text{Min}\{M[1][1] + M[2][3] + d_0d_1d_3, M[1][2] + M[3][3] + d_0d_2d_3\}$$
$$= \text{Min}\{0 + 24 + 40, 30 + 0 + 60\} = 64$$

$$M[2][4] = \text{Min}\{M[2][2] + M[3][4] + d_1d_2d_4, M[2][3] + M[4][4] + d_1d_3d_4\}$$
$$= \text{Min}\{0 + 72 + 36, 24 + 0 + 48\} = 72$$

$$M[1][4] = \text{Min}\{M[1][1] + M[2][4] + d_0d_1d_4, M[1][2] + M[3][4] + d_0d_2d_4$$
$$M[1][3] + M[4][4] + d_0d_3d_4\}$$
$$= \text{Min}\{0 + 72 + 60, 30 + 72 + 90, 64 + 0 + 120\} = 132$$

$$\begin{array}{cccccccc} A_1 & \times & A_2 & \times & A_3 & \times & A_4 & \times & A_5 & \times & A_6 \\ 5 \times 2 & & 2 \times 3 & & 3 \times 4 & & 4 \times 6 & & 6 \times 7 & & 7 \times 8 \\ d_0 & d_1 & d_1 & d_2 & d_2 & d_3 & d_3 & d_4 & d_4 & d_5 & d_5 & d_6 \end{array}$$

# The algorithm

---

```
int minmult (int n, const int d [], index P [][] )  
{  
  index i, j, k, diagonal;  
  int M [1 .. n][1 .. n];  
  for (i = 1; i <= n; i++) M[i][i] = 0;  
  for (diagonal = 1; diagonal <= n - 1; diagonal++) // Diagonal-1 is  
    for (i = 1; i <= n - diagonal; i++) { // just above the  
      j = i + diagonal; // main diagonal  
      M[i][j] = minimum (M[i][k] + M[k + 1][j] + d[i - 1]*d[k]*d[j]);  
                      i ≤ k ≤ j-1  
      P[i][j] = a value of k that gave the minimum;  
    }  
  return M[1][n];  
}
```

# Every-case time complexity

---

- Basic operation: instructions executed for each value of  $k$
- Input size:  $n$ , the number of matrices to be multiplied
- Time complexity

$$\sum_{diagonal \neq 1}^{n-1} [(n - diagonal) \times diagonal] = \frac{n(n-1)(n+1)}{6} \in \Theta(n^3)$$



# To obtain an optimal order from array $P$

---

	1	2	3	4	5	6
1		1	1	1	1	1
2			2	3	4	5
3				3	4	5
4					4	5
5						5

Figure 3.9 • The array  $P$  produced when Algorithm 3.6 is applied to the dimensions in Example 3.5.

□ What is the optimal order?

# Print optimal order

---

```
void order (index i, index j)
{
    if (i == j)
        cout << "A" << i;
    else {
        k = P[i] [j];
        cout << "(";
        order (i, k);
        order (k + 1, j);
        cout << ")";
    }
}
```

# Optimal Binary Search Trees

## درخت جستجوی دودویی بهینه

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- هر گره درخت دودویی حداکثر دو فرزند دارد.
- هر گره یک مقدار دارد
- فرزندان راست از مقدار گره بزرگتر و فرزندان چپ از مقدار این گره کوچکتر هستند.

# Examples

---

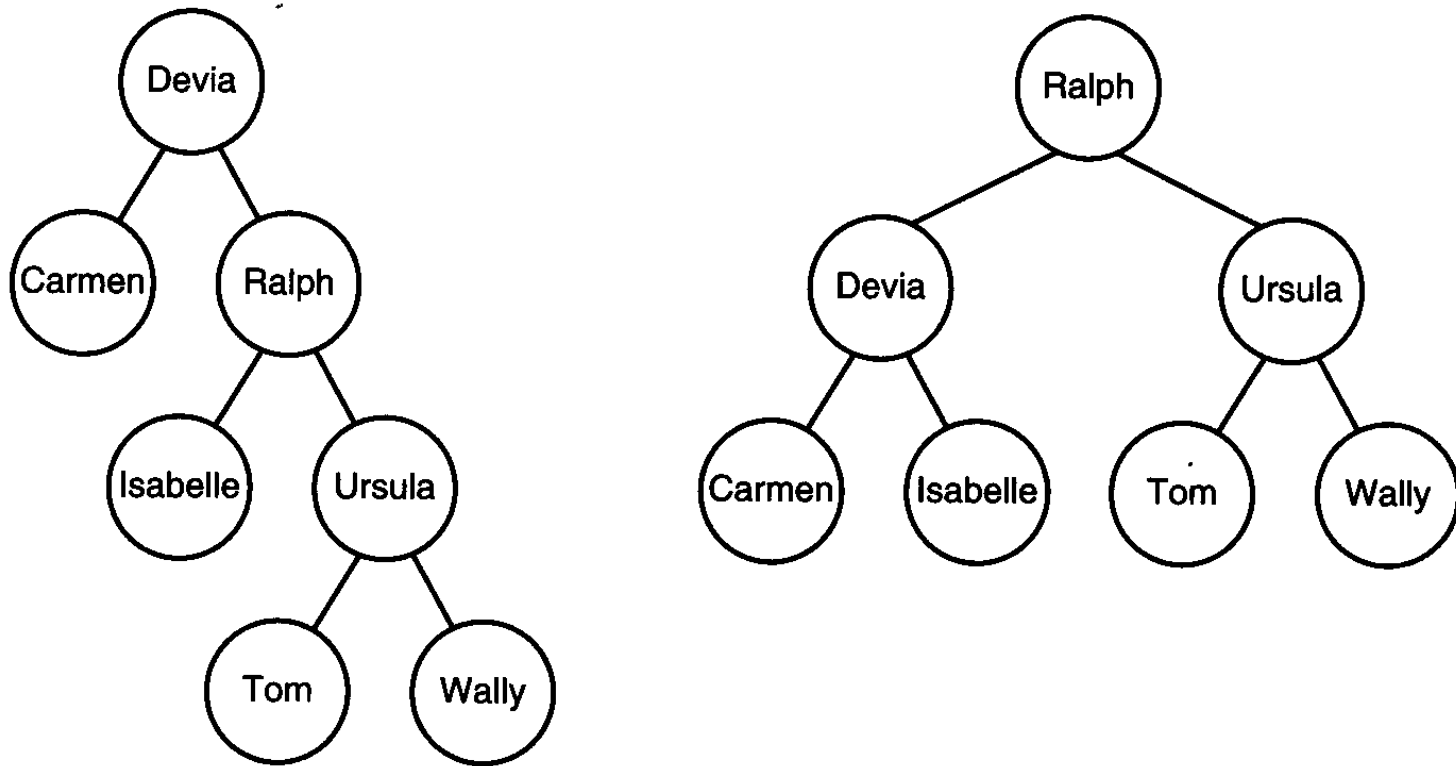


Figure 3.10 • Two binary search trees.

# Balanced tree

## درخت متوازن

---

- عمق (سطح) یک گره: تعداد یال‌ها در مسیر از ریشه تا گره.
- عمق درخت: حداکثر عمق تمام گره‌های درخت.
- درخت دودویی متعادل: عمق دو زیردرخت هر گره هرگز بیش از ۱ نیست.
- درخت جستجوی دودویی بهینه: میانگین زمان لازم برای یافتن یک کلید به حداقل می‌رسد.

# The search algorithm

---

## □ Algorithm 3.8: Search Binary Tree

Problem: Determine the node containing a key in a binary search tree. It is assumed that the key is in the tree.

```
void search (node_pointer tree, keytype keyin,  
             node_pointer& p)  
{  
    bool found;  
    p = tree; found = false;  
    while (! found)  
        if (p->key == keyin) found = true;  
        else if (keyin < p-> key);  
            p = p-> left; // Advance to left child.  
        else p = p-> right; // Advance to right child.  
}
```

# The average search time

## زمان جستجوی میانگین

---

- Search time: the number of comparisons done to locate a key
- Search time for *key* is:  $depth(key) + 1$
- The average search time:

$$\sum_{i=1}^n c_i p_i$$

Where  $n$  is the number of keys,  $p_i$  the probability that  $Key_i$  is the search key,  $c_i$  the number of comparisons needed to find  $Key_i$

# Find out the average search time

- $P_1 = 0.7,$   
 $P_2 = 0.2,$   
 $P_3 = 0.1$

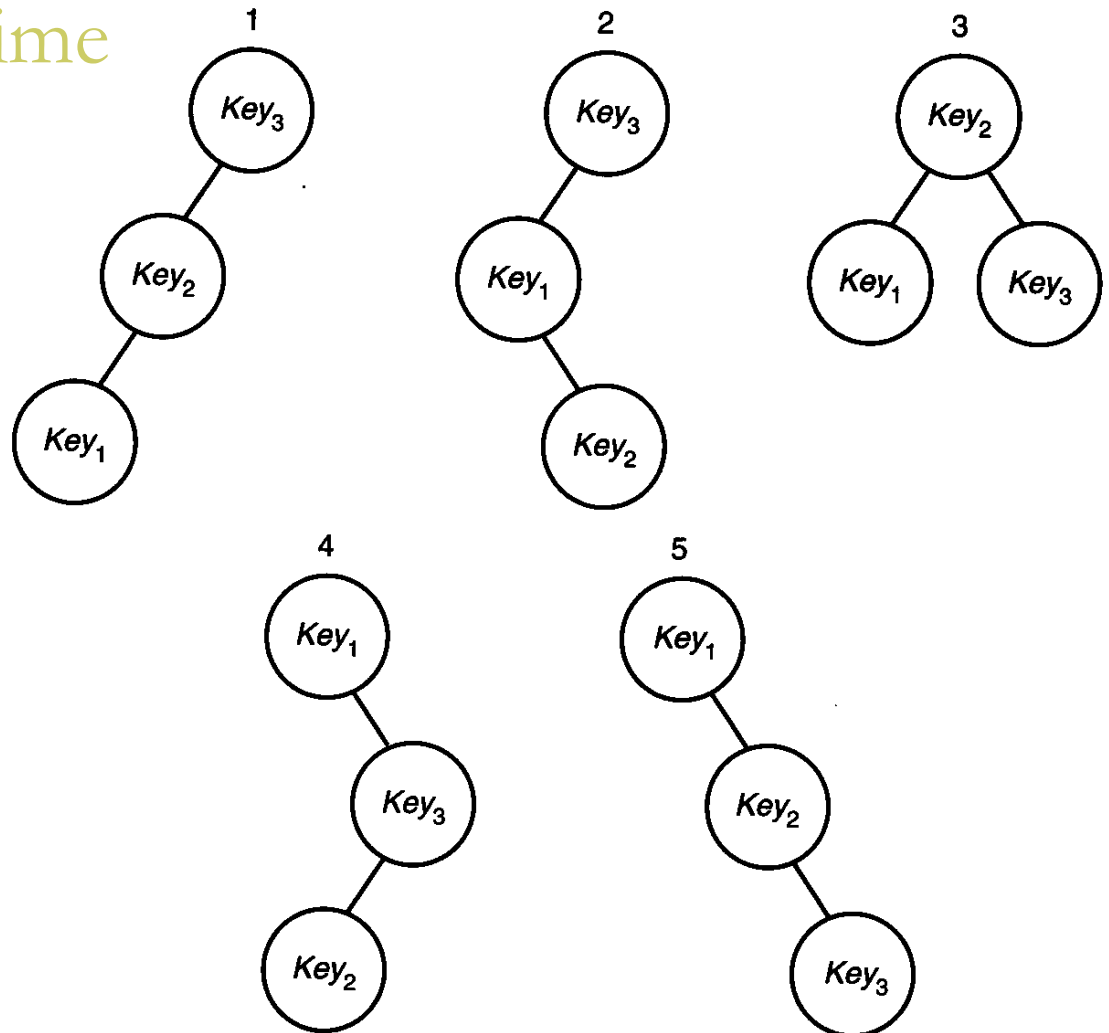


Figure 3.11 • The possible binary search trees when there are three keys.



# Brute force search complexity to find optimal solution

تعداد گره	تعداد درخت
۱	۱
۲	۲
۳	۵
۴	۱۴
۵	۴۲
۶	۱۳۲
...	
$n$	$\frac{1}{n+1} \binom{2n}{n}$



# To develop an efficient algorithm

---

□ Principle of optimality applies

□ Let  $A[i][j]$  = minimum value of  $\sum_{m=i}^j c_m p_m$

□  $A[i][i] = p_i$

# To search a key in Tree $k$

- Let Tree  $k$  be the optimal tree that  $Key_k$  is at the root

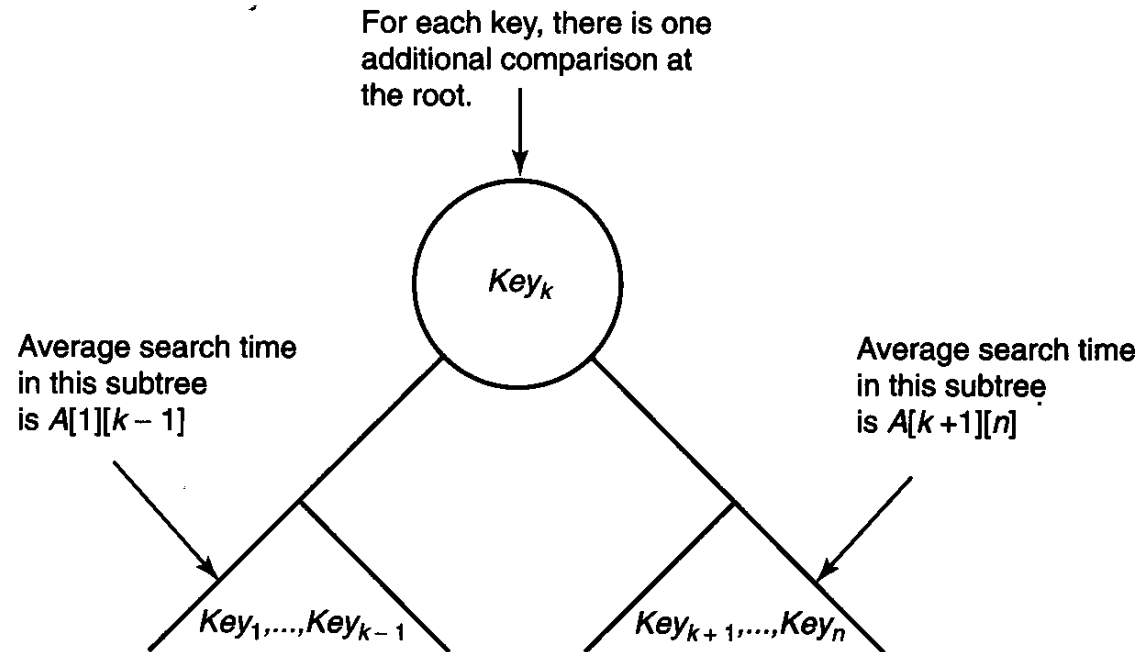


Figure 3.13 • Optimal binary search tree given that  $Key_k$  is at the root.

# The average search time

$$\underbrace{A[1][k-1]}_{\text{Average time in left subtree}} + \underbrace{p_1 + \dots + p_{k-1}}_{\text{Additional time comparing at root}} + \underbrace{p_k}_{\text{Average time searching for root}} + \underbrace{A[k+1][n]}_{\text{Average time in right subtree}} + \underbrace{p_{k+1} + \dots + p_n}_{\text{Additional time comparing at root}},$$

$$= A[1][k-1] + A[k+1][n] + \sum_{m=1}^n p_m$$

Recursive

$$A[1][n] = \underset{1 \leq k \leq n}{\text{Minimum}}(A[1][k-1] + A[k+1][n]) + \sum_{m=1}^n p_m$$

$$A[i][j] = \underset{i \leq k \leq j}{\text{minimum}}(A[i][k-1] + A[k+1][j]) + \sum_{m=i}^j p_m \quad i < j$$

$$A[i][i] = p_i$$

$A[i][i-1]$  and  $A[j+1][j]$  are defined to be 0.

# The algorithm(Matrix initialization)

---

```
for (i = 1; i <= n; i++)  
{  
    A[i][i - 1] = 0;  
    A[i][i] = p[i];  
    R[i][i] = i;  
    R[i][i - 1] = 0;  
}  
A[n + 1][n] = 0;  
R[n + 1][n] = 0;
```

# The algorithm (cont'd)

---

```
for (diagonal = 1; diagonal <= n - 1; diagonal ++)  
  for (i = 1; i <= n - diagonal; i ++)  
  {  
    j = i + diagonal;  
     $A[i][j] = \text{minimum} (A[i][k - 1] + A[k + 1][j]) + \sum_{m=i}^j P_m$   
     $R[i][j] = \text{a value of } k \text{ that gave the minimum;}$   
     $i \leq k \leq j$   
  }  
minavg  $A[1][n]$ ;
```

# Every-case time complexity

---

- Basic operation: The instructions executed for each value of  $k$
- Input size:  $n$ , the number of keys
- Time complexity:

$$T(n) = \frac{n(n-1)(n+4)}{6} \in \Theta(n^3)$$

# Build optimal binary search tree

---

```
node_pointer tree (index i, j)
{
    index k;
    node_pointer p;
    k = R[i][j];
    if (k == 0)
        return NULL;
    else{
        p = new nodetype;
        p->key = Key[k];
        p->left = tree(i, k - 1);
        p->right = tree (k + 1, j);
        return p;
    }
}
```



$$A[1][n] = \underset{1 \leq k \leq n}{\text{Minimum}}(A[1][k-1] + A[k+1][n]) + \sum_{m=1}^n p_m$$

## Example (1)

- Keys:            Don        Isabelle   Ralph    Wally  
                   Key[1]   Key[2]   Key[3]   Key[4]  
                    $p_1=3/8$     $p_2=3/8$     $p_3=1/8$     $p_4=1/8$
- Arrays produced

	0	1	2	3	4
1	0	$\frac{3}{8}$	$\frac{9}{8}$	$\frac{11}{8}$	$\frac{7}{4}$
2		0	$\frac{3}{8}$	$\frac{5}{8}$	1
3			0	$\frac{1}{8}$	$\frac{3}{8}$
4				0	$\frac{1}{8}$
5					0

*A*

	0	1	2	3	4
1	0	1	1	2	2
2		0	2	2	2
3			0	3	3
4				0	4
5					0

*R*

Figure 3.14 • The arrays *A* and *R*, produced when Algorithm 3.9 is applied to the instance in Example 3.9.

# The resultant tree

---

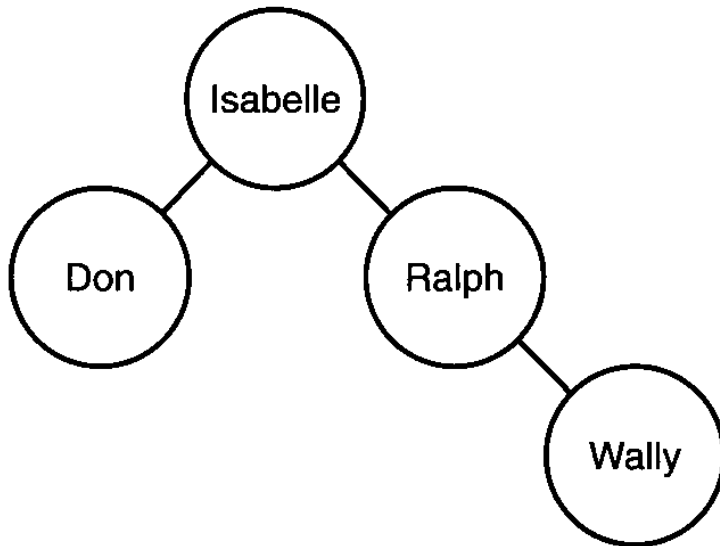


Figure 3.15 • The tree produced when Algorithms 3.9 and 3.10 are applied to the instance in Example 3.9.

$$A[1][n] = \underset{1 \leq k \leq n}{\text{Minimum}}(A[1][k-1] + A[k+1][n]) + \sum_{m=1}^n p_m$$

## Example (2)

□ Keys:

A	B	C	D
$p_1=1/8$	$p_2=4/8$	$p_3=1/8$	$p_4=2/8$

Initialization

	<b>0</b>	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>
<b>1</b>	0	1/8			
<b>2</b>		0	4/8		
<b>3</b>			0	1/8	
<b>4</b>				0	2/8
<b>5</b>					0

A =

$$A[1][n] = \underset{1 \leq k \leq n}{\text{Minimum}}(A[1][k-1] + A[k+1][n]) + \sum_{m=1}^n p_m$$

## Example (2) ...

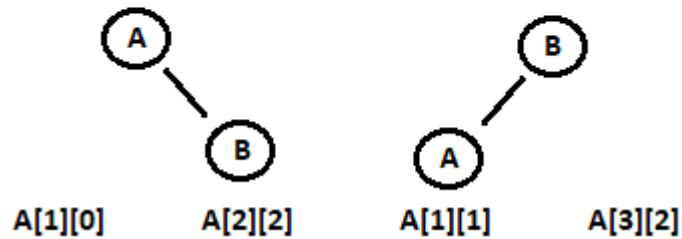
□ Keys:

A	B	C	D
$p_1=1/8$	$p_2=4/8$	$p_3=1/8$	$p_4=2/8$

	0	1	2	3	4
1	0	1/8	?		
2		0	4/8		
3			0	1/8	
4				0	2/8
5					0

$$A[1][2] = \min\{A[1][0]+A[2][2], A[1][1]+A[3][2]\}$$

$$+1/8+4/8 = 6/8$$



$$A[1][n] = \underset{1 \leq k \leq n}{\text{Minimum}}(A[1][k-1] + A[k+1][n]) + \sum_{m=1}^n p_m$$

## Example (2) ...

□ Keys:

A	B	C	D
$p_1=1/8$	$p_2=4/8$	$p_3=1/8$	$p_4=2/8$

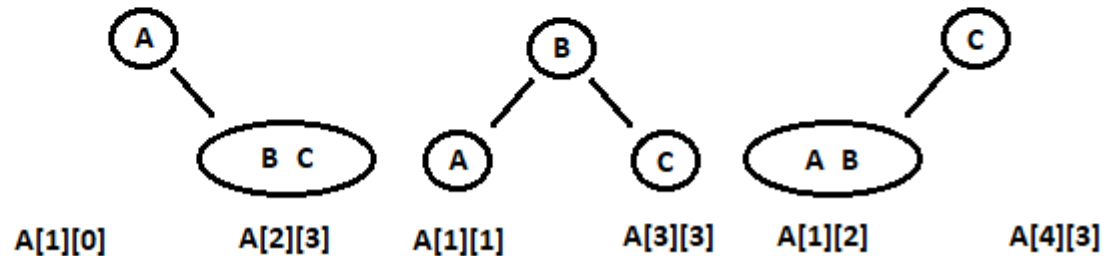
	0	1	2	3	4
1	0	1/8	6/8	?	
2		0	4/8	6/8	
3			0	1/8	4/8
4				0	2/8
5					0

$$A[1][3] = \min\{A[1][0]+A[2][3],$$

$$A[1][1]+A[3][3],$$

$$A[1][2]+A[4][3]\}$$

$$+1/8+4/8+1/8$$



# The traveling sales person problem

## مساله فروشنده دوره گرد

---

- Tour (Hamilton circuit): a path from a vertex to itself that passes through each of the other vertices exactly once
- Optimal tour: such a path of minimum length
- Brute force algorithm is  
 $(n-1)(n-2)\cdots 1 = (n-1)!$
- Principle of optimality applies

# Representation of the graph

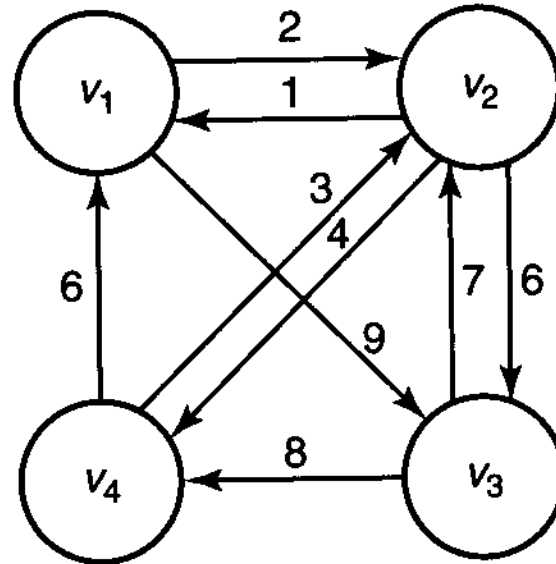


Figure 3.16 • The optimal tour is  $[v_1, v_3, v_4, v_2, v_1]$ .

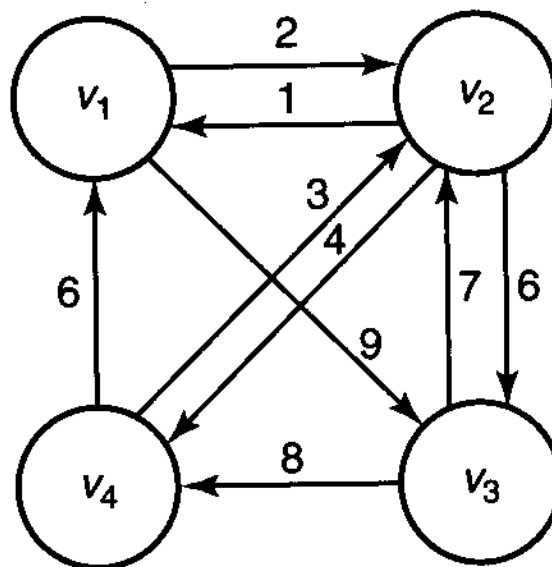
	1	2	3	4
1	0	2	9	$\infty$
2	1	0	6	4
3	$\infty$	7	0	8
4	6	3	$\infty$	0

Figure 3.17 • The adjacency matrix representation  $W$  of the graph in Figure 3.16.

# Preparation

---

- Let  $D[v_i][A]$  = length of a shortest path from  $v_i$  to  $v_1$  passing through each vertex in  $A$  exactly once
- Compute  $D[v_2][A]$  when  $A = \{v_3\}$  and  $A = \{v_3, v_4\}$





# The algorithm

---

- Length of an optimal tour =

$$\mathit{Minimum}_{2 \leq j \leq n} (W[1][j] + D[v_j][V - \{v_1, v_j\}])$$

- In general for  $i \neq 1$  and  $v_i$  not in  $A$

$$D[v_i][A] = \mathit{Minimum}_{j: v_j \in A} (W[i][j] + D[v_j][A - \{v_j\}]) \quad \text{if } A \neq \phi$$

$$D[v_i][\phi] = W[i][1]$$

# Compute the optimal tour

---

	1	2	3	4
1	0	2	9	$\infty$
2	1	0	6	4
3	$\infty$	7	0	8
4	6	3	$\infty$	0

Figure 3.17 • The adjacency matrix representation  $W$  of the graph in Figure 3.16.

# The Algorithm

---

```
void travel (int n, const number W[][], index P[][], number& minlength)
{
  index i, j, k;
  number D[1..n][subset of V - {v1}];
  for (i = 2; i <= n; i++) D[i][∅] = W[i][1];

  for (k = 1; k <= n - 2; k++)
    for (all subsets A ∈ V - {v1} containing k vertices)
      for (i such that i ≠ 1 and vi is not in A){
        D[i][A] = minimum (W[i][j] + D[j][A - {vj}]);
                    j: vj ∈ A
        P[i][A] = value of j that gave the minimum;
      }
  D[1][V - {v1}] = minimum (W[1][j] + D[j][V - {v1, vj}]);
                    2 ≤ j ≤ n
  P[1][V - {v1}] = value of j that gave the minimum;
  minlength = D[1][V - {v1}];
}
```

# Time complexity

---

$$\sum_{k=1}^n k \binom{n}{k} = n 2^{n-1}$$

$$T(n) = \sum_{k=1}^{n-2} (n-1-k) k \binom{n-1}{k}.$$

$$(n-1-k) \binom{n-1}{k} = (n-1) \binom{n-2}{k}.$$

$$T(n) = (n-1) \sum_{k=1}^{n-2} k \binom{n-2}{k}.$$

# Every-case time complexity

---

- Basic operation: the instructions executed for each value of  $v_j$
- $n$ , the number of vertices in the graph
- Time complexity  
$$T(n) = (n-1)(n-2)2^{n-3} \in \Theta(n^2 2^n)$$
- Memory complexity:  
$$M(n) = 2 \times n2^{n-1} = n2^n \in \Theta(n2^n)$$

# Catalan Number



عدد کاتالان

- **کاتالان** در ریاضیات ترکیبی، نام یک سری از اعداد طبیعی است که در مسائل شمارشی کاربرد دارد.
- این سری به افتخار ریاضیدان بلژیکی **شارل کاتالان** (قرن نوزدهم) نام نهاده شد.

<b>N</b>	<b>Catalan</b>	<b>Fibonacci</b>
0	1	0
1	1	1
2	2	1
3	5	2
4	14	3
5	42	5
6	132	8
7	429	13
8	1430	21
9	4862	34
...	...	...
20	6564120420	6765



## رابطه کاتالان

---

$$C_n = \frac{1}{n+1} \binom{2n}{n} = \frac{(2n)!}{(n+1)!n!} \quad \text{for } n \geq 0.$$

$$C_0 = 1 \quad \text{and} \quad C_{n+1} = \sum_{i=0}^n C_i C_{n-i} \quad \text{for } n \geq 0.$$

$$C_0 = 1 \quad \text{and} \quad C_{n+1} = \frac{2(2n+1)}{n+2} C_n,$$

# مسایل کاتالانی - پرانتز گذاری

---

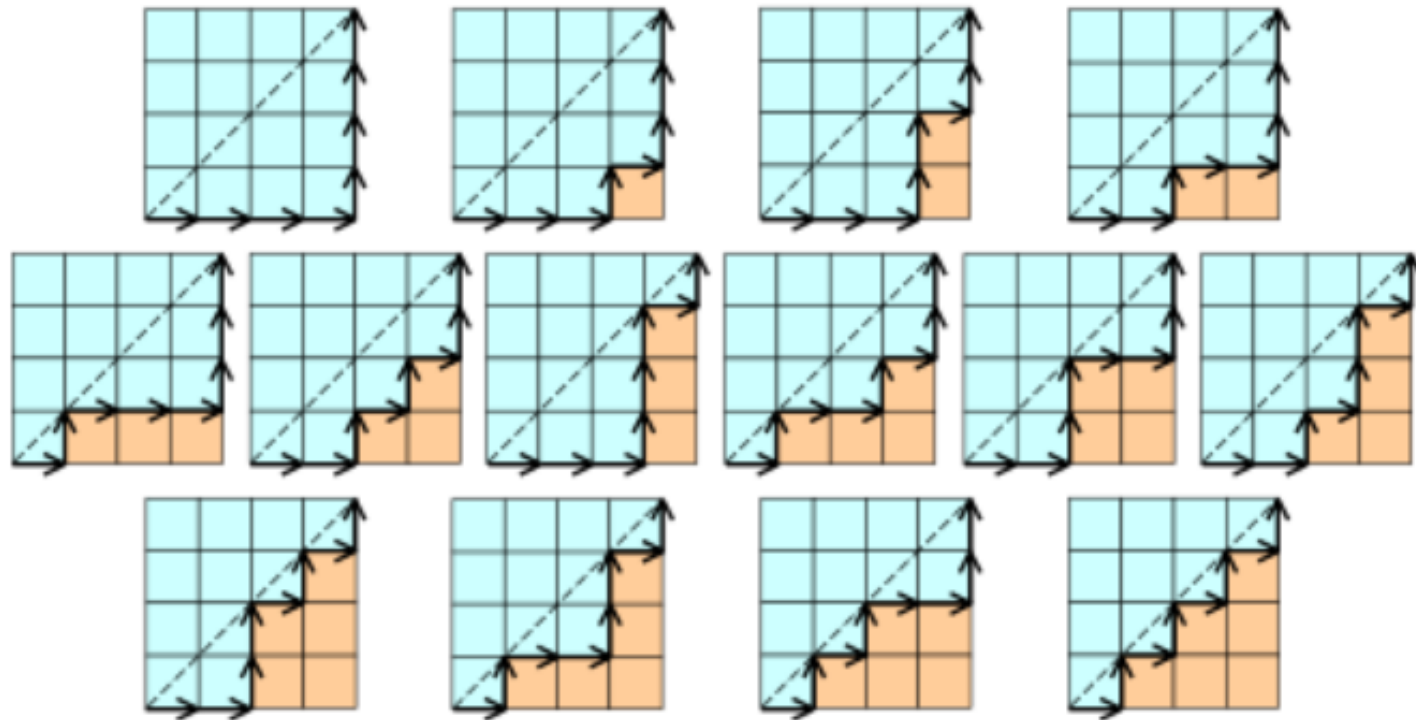
- تعداد راه‌های مختلفی است که چند عامل می‌توانند پرانتز گذاری شوند.
- مساله ضرب ماتریس‌ها
- ضرب تعداد  $n =$

$$((ab)c)d \quad (a(bc))d \quad (ab)(cd) \quad a((bc)d) \quad a(b(cd))$$

# مسایله کاتالانی

## مسیرهای پایین قطر غیر نزولی

□ تمام مسیرهای غیر نزولی پایین قطر فرعی برای رسیدن از مبدا به مقصد

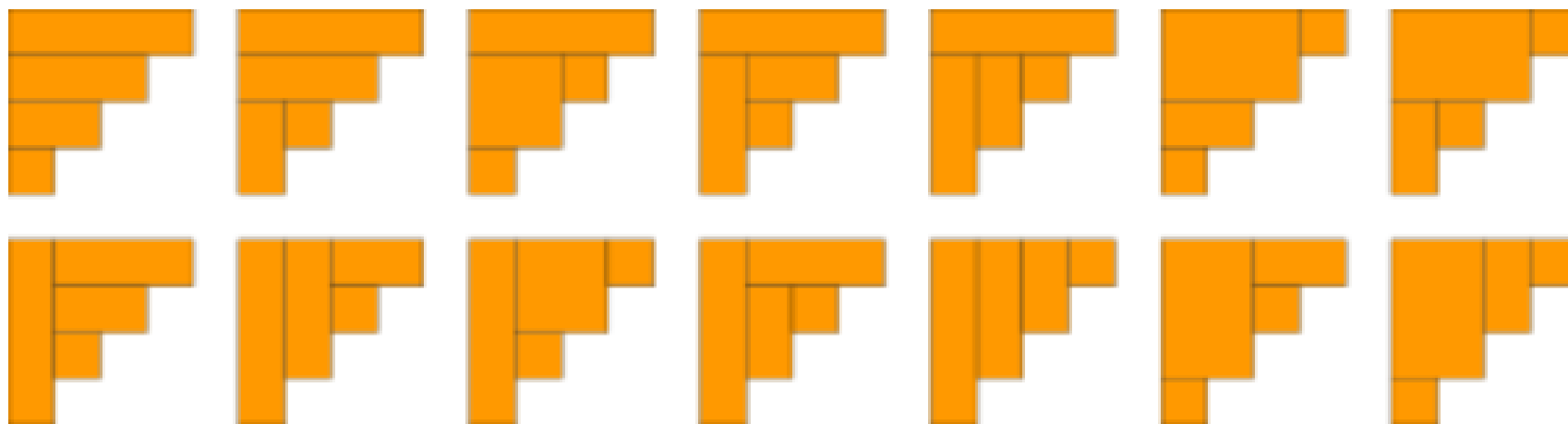


# مسایل کاتالانی

تمام حالت‌های ممکن کاشی‌کاری راه پله  $n \times n$  با  $n$  کاشی

---

□  $N = 4$



# مسایلی کاتالانی-مثلث بندی چندضلعی محدب

